Level

244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART[®] and FOUNDATION Fieldbus, SIL Safety Information

MI EML0710S

Instruction

Release date July 2024





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Important Safety Instructions

Read these instructions carefully and look at the equipment to become familiar with it before trying to install, operate, service, or maintain it. The following safety messages might appear throughout this manual or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a "Danger" or "Warning" safety message indicates that an electrical hazard exists that results in personal injury if the instructions are not followed.



This safety alert symbol that lets you know about potential personal injury hazards. Obey all safety messages with this symbol to avoid possible injury or death.

DANGER indicates a hazardous situation which, if not avoided, **will result in** death or serious injury.

Failure to follow these instructions will result in death or serious injury.

WARNING indicates a hazardous situation that, if not avoided, **could result in** death or serious injury.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

CAUTION indicates a hazardous situation that, if not avoided, **could result in** minor or moderate injury.

Failure to follow these instructions can result in injury or equipment damage.

NOTICE

NOTICE is used to address practices not related to physical injury.

Failure to follow these instructions can result in equipment damage.

Please Note

Electrical equipment should only be installed, operated, serviced, and maintained by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction, installation, and operation of electrical equipment and has received safety training to recognize and avoid the hazards involved.

Scope of Application

The intelligent transmitter 244LD LevelStar measures the level, interface and density of liquids continuously in processes of all industrial applications which meet the particular demands on safety equipment required according to IEC 61508 / IEC 61511-1.

Features

- · Functional safety in compliance with IEC 61508 / IEC 61511-1
- · Suitable for use up to SIL 2, independently assessed by exida.com
- Explosion protection (depending on the version)
- Electromagnetic compatibility to EN 61326 and NAMUR recommendation NE21

General

The scope of application encompasses the intelligent transmitters for level, interface and density of type 244LD LevelStar (HART and 4-20 mA without communications) for continuous measurement.

The measurement is based on the Archimedes buoyancy principle. The devices can be accessed and adjusted remotely using a PC or hand terminal but can also be adjusted by conventional means with local pushbuttons. The transmitters are suitable for use in explosion hazard zones.

Other features:

- Continuous self-diagnosis
- Configurable safety level
- Software locking for pushbuttons and reconfiguration
- Simple commissioning
- · Measurements virtually independent of the product properties

The intelligent transmitters for level, interface, and density 244LD LevelStar can be employed in applications with low or high demand rates. For more technical information, see 244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART® and FOUNDATION Fieldbus, (PSS EML0710) and 244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART® and FOUNDATION Fieldbus, (MI EML0710).

Identification

This safety manual is valid for all devices 244LD LevelStar:

- Model Code: 244LD-xxxxxNxxxx-Q
- Revision: 6.2.x with Software 8.29.x (Communication HART 5)
- Revision: 7.0.x with Software 9.29.x (Communication HART 7)
- DMU DTM Version 3.5.1 or higher (Communication HART 5)
- LevelStar DTM Version 1.1.0 or higher (Communication HART 7)

Requirements

Requirements for applications under the specific demands on safety equipment according to IEC 61508/IEC 61511-1.

Project Planning

The technical data specified in 244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART® and FOUNDATION Fieldbus, (PSS EML0710), particularly with regard to the application and ambient conditions, are fulfilled by the transmitters. The average operating temperature for the amplifier over longer periods is not higher than 40°C.

HART Communication

In case of using a DCS for HART configuration it is necessary to ensure using the correct HART communication link, for example, by checking the tag number and write protection status.

Commissioning

Conduct function test on the transmitters after project planning. The necessary tests must be specified in the safety manual of the system. The tests include:

- Zero point verification
- Measured value verification
- Simulation of various measured values
- Verification of the preset safety values
 - **NOTE:** Conduct function test for remote adjustment of the parameters relevant to measurements.

Entering Safety Mode

Before the safety mode is put into operation, a verification of all parameters must be performed. Steps to follow:

- 1. Restart the device via DTM or power cycle.
- 2. Upload all data within DTM.
- 3. Verify and confirm the configuration of all parameters by using the confirmation screen within the DTM.
- 4. Lock the HART communications and local operation by activating the write protection/entering the safety mode.

Regular Function Tests

Regular function tests (see Recurring Tests of the Transmitter for Level, Interface and Density, page 12) must be conducted.

Other Requirements

The infrared service interface is intended for special authorized Schneider Electric personnel for debug purposes only.

Relevant Standards

- DIN EN 61508 Parts 1 to 7: Functional safety-related electric/electronic/ programmable electronic systems
- DIN IEC 61511 Parts 1 to 3: Functional safety Safety instrumented systems for industrial processes

Terms

The terms listed are defined according to DIN EN 61508 Teil 1-7 Beuth-Verlag, Berlin, Part 4 and DIN IEC 61511 Teil 1-3 Beuth-Verlag, Berlin, Part 1.

| Term | Description |
|----------------------------------|--|
| Actor | Component of a safety instrumented system which executes actions in the process to achieve a safe situation. |
| Failure | Loss of the ability of a functional unit to execute the required function. |
| Diagnostic coverage | Ratio of the failure rate of the faults detected by diagnostic tests to the overall failure rate of the components or subsystem. The diagnostic rate does not include faults detected by recurring tests. |
| Fault | Abnormal situation which can cause an impairment or loss of the ability of a functional unit to execute a required function. |
| Functional safety | Part of overall safety relating to the process and BPCS and dependent on the intended function of the SIS and other safety levels. |
| Functional unit | Unit consisting of hardware or software or both which is suitable to execute a defined task. |
| Dangerous failure | Failure with the potential of putting the safety instrumented system in a hazardous or dysfunctional condition. |
| Safety | Freedom of disproportionate risks. |
| Safety function | Function executed by an SIS, a safety-related system of other equipment or external facilities to reduce risks with the objective of achieving or upholding the safe conditions of a process, taking account of a defined, detected dangerous event. |
| Safety integrity | Mean probability that a safety instrumented system will execute the required safety functions under all defined conditions within a defined period. |
| Safety integrity level (SIL) | One of four discreet stages to specify the requirements for the safety integrity of the safety functions assigned to the safety instrumented system, in which safety integrity level 4 represents the highest degree of safety integrity and safety integrity 1 represents the lowest. |
| Safety instrumented system (SIS) | Safety instrumented system to execute one or more safety functions. An SIS consists of one or more sensors, a logic system, and actor(s). |
| Non-dangerous failure | Failure without the potential of putting the safety instrumented system in a hazardous or dysfunctional condition. |

Abbreviations

| Abbreviation | Description | |
|--------------|------------------------------|--|
| BPCS | Basic process control system | |
| DC | Diagnostic coverage | |

244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART $^{\otimes}$ and FOUNDATION Fieldbus, SIL Safety Information

| Abbreviation | Description |
|--------------|--|
| HFT | Hardware fault tolerance |
| PFD | Probability of failure on demand |
| PFDAVG | Average probability of failure on demand |
| SFF | Safe failure fraction |
| SIL | Safety integrity level |
| SIS | Safety instrumented system |

Design Tables

The tables below are used to determine the Safety Integrity Level (SIL).

Mean Probability of a Failure on Demand (PFD_{AVG})

This table reflects the achievable safety integrity level (SIL) in dependency on the mean probability of a failure on demand. The specified failure tolerances in this case apply to a safety function operated in the mode with low demand rate (see DIN EN 61508 Teil 1-7 Beuth-Verlag, Berlin Part 1, Chapter 7.6.2.9).

| Safety integrity level (SIL) | PFD _{AVG} with low demand rate |
|------------------------------|---|
| 4 | 10 ⁻⁵ to < 10 ⁻⁴ |
| 3 | 10 ⁻⁴ to < 10 ⁻³ |
| 2 | 10 ⁻³ to < 10 ⁻² |
| 1 | 10 ⁻² to < 10 ⁻¹ |

Probability of a Dangerous Failure per Hour (PFH)

If the requirement rate is more than once per year or greater than twice the frequency of recurring tests, the measurement system must be employed in the mode with high demand rate (see DIN EN 61508 Teil 1-7 Beuth-Verlag, Berlin Part 1, Chapter 3.5.12).

| Safety Integrity Level (SIL) | PFH with high demand rate Probability of a dangerous failure per hour |
|------------------------------|---|
| 4 | 10 ⁻⁹ to < 10 ⁻⁸ |
| 3 | 10 ⁻⁸ to < 10 ⁻⁷ |
| 2 | 10 ⁻⁷ to < 10 ⁻⁶ |
| 1 | 10 ⁻⁶ to < 10 ⁻⁵ |

Safety Integrity of the Hardware

This table shows the achievable Safety Integrity Level (SIL) in dependency on the proportion of non-dangerous failures (SFF) and the fault tolerance of the hardware (HFT) for safety-related type B sub-systems (see DIN EN 61508 Teil 1-7 Beuth-Verlag, Berlin Part 2, Chapter 7.4.3.1.4).

| Proportion of non- | Fault tolerance of the hardware (HFT) | | | | |
|--------------------------|---------------------------------------|----------|-------|--|--|
| dangerous failures (SFF) | 0 | 1(0) (a) | 2 | | |
| < 60% | Not permitted | SIL 1 | SIL 2 | | |
| 60% - < 90% | SIL 1 | SIL 2 | SIL 3 | | |
| 90% - < 99% | SIL 2 | SIL 3 | SIL 4 | | |
| ≤ 99% | SIL 3 | SIL 4 | SIL 4 | | |

NOTE:

(a) According to DIN IEC 61511 Teil 1-3 Beuth-Verlag, Berlin Part 1, Chapter 11.4.4, the fault tolerance of the hardware (HFT) may be reduced by one (values in brackets) in subsystems such as sensors and actors if the employed device fulfills all of the following conditions:

- The device is validated in practice.
- Only process-relevant parameters can be changed at the device.
- Changes of the process-relevant parameters are protected (for example, password, jumpers and so on).
- The function has a required safety integrity level lower than 4.

Safety-related System

A safety-related system usually consists of the three subsystems input subsystem (sensor), logic sub-system (PLC or control system) and output subsystem (actuator). The Mean Probability of a Failure on Demand (PFD_{AVG}) is usually divided as follows:



Safety Function, Restrictions and Behavior

Safety Function

The safety related output signal is the 4-20 mA analog output signal. All safety measures refer to this output signal exclusively.

The logic subsystem (for example, DCS) must scan the field device with a scan rate of <500 ms for proper fault detection of the transmitter.

While running a safety application, the additional HART communication can be used to get additional diagnostic information.

Restrictions for Use in Safety Related Applications

The requirements described in Requirements, page 6 as well as all specifications for correct operation of the device must be fulfilled carefully for usage of the device within a safety related application.

The dangerous failure mode within the meaning of the safety characteristics given by Characteristics, page 13 is given by all detected failures leading to output accuracy worse than 2%.

Behavior during Operation and Malfunctions

For malfunctions the behavior of the output is defined according to NAMUR recommendation NE43:

- Up-scale the output current: ≥ 21 mA
- Down-scale the output current: ≤ 3.6 mA

Down Scaling is used in case of a detected fault, where the internal watchdog of the device is no longer triggered.

Up Scaling is used in case of a detected fault where the output can be controlled by the internal software.

Examples for these detections:

- Temperature out of range
- Internal Reference Voltages out of range
- Output Current not correct
- AD-Converter not working properly

Safety Relevant Configuration Parameters

Verify the following parameters before entering the safety mode using the confirmation screen as describe in Entering Safety Mode, page 6.

Table 1 - Safety Relevant Configuration Parameters

| Name | Description |
|--------------------------|--|
| Smart Smoothing Damping | Integration Time of Smart Smoothing |
| Smart Smoothing Deadband | Deadband of Smart Smoothing |
| Zeropoint Mode | Mode of Zeropoint offset correction |
| Zeropoint Basic | Zeropoint of the sensor |
| Zeropoint Offset | Zeropoint Offset used in automode |
| Zeropoint Special Offset | Special zeropoint offset used in manual mode |
| Upper Range Value | Lower Range Value of measuring range (that is, weight of the displacer in case of an empty tank) |
| Lower Range Value | Upper Range Value of measuring range |
| Characterization | Characterization of the output |
| Output Damping | Damping of the output signal |

Recurring Tests of the Transmitter for Level, Interface and Density

Safety Tests

According to IEC 61508/61511, the safety function of the entire safety loop must be tested regularly. The test intervals necessary for this purpose are defined in the calculation of the respective safety loop.

Function Test

The orderly function of the transmitter for level, interface and density must be tested regularly every 5 years. The test may be conducted by the manufacturer or an authorized workshop. The following work must be conducted:

- 1. Dismantle the sensor.
- 2. Examine the torsion tube to detect corrosion and leaks (replace if necessary).
- 3. Examine the sandwich housing support for dirt (clean or replace if necessary).
- 4. Examine the ball bearing in base plate for easy action.
- 5. Replace the sealing rings in the sensor (use Cu-based grease).
- 6. Examine the sealing rings in the amplifier and replace as necessary (apply grease).
- 7. Observe the tightening torques for the screws specified in the 244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART® and FOUNDATION Fieldbus, (MI EML0710) when assembling.
- 8. Power on the device to initiate self test procedure.
- 9. Adjust the transmitter as described in 244LD LevelStar Intelligent Buoyancy Transmitter for Level, Interface and Density – HART® and FOUNDATION Fieldbus, (MI EML0710).
- 10. Adjust the safety range.
- 11. Verify all adjustments by setting to the zero point, the end value, a medium value (for example, 50% value) and the safety settings. In case of using a non-linear characterization curve the relevant points must be verified.
- 12. Verify the temperature measurement of the sensor and electronics.
- 13. Verify the alarm levels with the DTM-function "Error State Test".
- 14. Lock the settings by entering the Safety Mode as described in Entering Safety Mode, page 6

The transmitter for level, interface and density of types 244LD LevelStar is subject to the pressure equipment directive (DGRL 97/23/EC). The intervals for recurring tests specified in the 244LD LevelStar, Safety Operating Instructions, (MI EML0010-Ex) must therefore be observed (according to German BertrSichV dated 27.09.2002). [Rev.6].

Repairs

Detected defective units are sent to the repair department of Schneider Electric with a precise description of the fault and the cause.

Safety Characteristics

Information not included in this summary is contained in Management Summary, page 17.

Assumptions

The specified characteristics are applicable under the following assumptions:

- · The requirements stated in Requirements, page 6 are fulfilled.
- The repair time (MTTR) after a device has failed is 24 hours.
- Test interval: \leq 5 years.
- Diagnostic time: < 5 min

Characteristics

| Unit Type | HFT | SFF | PFD _{AVG} | PFH | λ _{DU} | λ_{DD} | λ _{su} | λ_{SD} |
|--------------|-----|-----|--------------------|------------|-----------------|----------------|-----------------|----------------|
| В | 0 | 92% | 1.02E-03 | < 0.42E-07 | 42 FIT | 502FIT | 0 FIT | 0 FIT |

The probability of a dangerous failure per hour (PFH) is based on an error response time < 5 min and a demand rate of > 500 min.

The failure rates are valid for the useful life of the instrument. According to section 7.4.7.4 note 3 of DIN EN 61508 part 2 DIN EN 61508 Teil 1-7 Beuth-Verlag, Berlin, the useful lifetime ranges between 8 to 12 years.

Declaration of Conformity

Figure 1 - Page 1 of EU/SIL Declaration of Conformity

| | Schneider Electric |
|---|--|
| EU/SIL DE | CLARATION OF CONFORMITY |
| Ve, Manufacturer: Eckardt SAS (Subsidiary of Schneider Elect FR-93500 Rueil Malmaison) 20 rue de la Marne FR-68360 Soultz Hereby declare under our sole respons | ric Industries SAS bility that the products: |
| Product Type | 2441 D. Type AID421, AD931, AD432, AD432 A/B |
| List of reference and options | See next pages |
| re in conformity with the requirements of llowing standards. Directive | of the following directives and conformity was checked in accordance with the Harmonized Standard |
| | AD 2000-Code resp. EN 13445 |
| PED Directive 2014/68/EU | Applied conformity assessment procedures: Module H Module B For these products the following EU-Certificate exists: DGR-0036-QS-1308-19 Z-IS-AN3-STG-19-11-2974395-06143258 Z-IS-AN3-STG-19-11-2974395-06152151 Z-IS-AN3-STG-19-11-2974395-06152151 Z-IS-AN3-STG-19-11-2974395-06154417 Z-IS-AN3-STG-19-11-2974395-06154417 Z-IS-AN3-STG-19-11-2974395-06160046 Z-IS-AN3-STG-19-11-2974395-07082001 Z-IS-AN3-STG-19-11-2974395-07082001 Z-IS-AN3-STG-19-11-2974395-07082001 Z-IS-AN3-STG-19-11-2974395-0613002 Z-IS-AN3-STG-19-11-2974395-06143621 Z-IS-AN3-STG-19-11-2974395-0614201 Z-IS-AN3-STG-19-11-2974395-0614201 Z-IS-AN3-STG-19-11-2974395-0614205 Z-IS-AN3-STG-19-11-2974395-06142055 Z-IS-AN3-STG-19-11-2974395-07082501 Z-IS-AN3-STG-19-11-2974395-07082501 Z-IS-AN3-STG-19-11-2974395-07082501 Z-IS-AN3-STG-19-11-2974395-07092548 Notified Body: TÜV SÜD Industrie Service GmbH, Westendstr. 199, D-80686 München Notified Body no.0036 |
| EMC Directive 2014/30/EU | EN 55011:2009+A1:2010 Industrial, scientific and medical equipment - Radio-frequency disturbance characteristics - Limits and methods of measurement EN 61326:2013 Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 1: General requirements EN IEC 60079-0:2018 Evolosity eatmospheres - Part 0: Enument. |
| ATEX Directive 2014/34/EU | General requirements EN 60079-1:2014 Equipment protection by flameproof enclosures "d" EN 60079-11:2012 Explosive atmospheres - Part 11: Equipment protection by intrinsic safety "l" EN 60079-26:2015 Explosive atmospheres - Part 26: Equipment with equipment protection level (EPL) Ga AID421 + AD432. Protection String(s): |

Figure 2 - Page 2 of EU/SIL Declaration of Conformity

| | EU/SIL DECL | _AR | |
|---|--|---------------------------|---|
| | | | 931 + AD432- Protection String(s): |
| | | EN | IEC 63000:2018 Technical documentation for the assessme |
| RoHS Direct (Inclusive of | tive 2011/65/EU f Directive (EU) 2015/863) | elec | ctrical and electronic products with respect to the restriction o |
| | SIL Proof test interval | | 2 ≤ 5 Jahre / Years |
| | Proof test interval | | ≤ 5 Jahre / Years |
| | HFT | | 0 ¹⁾ (Single channel using) |
| | SFF | | 92% |
| | PFD _{avg} | | 1,02x10-3 |
| | PFH ²) | | < 0,42 x 10 ⁻⁷ |
| | λdd | | 502 FIT |
| | λ _{su} | | 0 FIT |
| | λ _{sd} | | 0 FIT |
| | MTTF 3) | | 210 Jahre / Years |
| | ¹⁾ Accor | ding to | 92% o chapter 11.4.4 of IEC 61511-1 |
| Subject to corre- standards, to th This declaration Steve to Corre- Steve to Corre- | ect installation, maintenance a le supplier's instructions and i becomes invalid in the case | and us to acc of an | e onforming to its intended purpose, to the applicable regu septed rules of the art. y modification to the products not authorized by us. |
| Process Autom Industrial Auto Schneider Elect | npliance Engineering ation R&D mation Business tric | | |

Figure 3 - Page 3 of EU/SIL Declaration of Conformity



Management Summary

Certificate / Certificat Zertifikat / 合格証 FOX 1012062 P0009 C004 exida hereby confirms that the: 244LD LevelStar The manufacturer may use the mark: Eckardt S.A.S. A company in the Schneider Electric Group Soultz, France Has been assessed per the relevant requirements of: IEC 61508 : 2010 Parts 1-3 and meets requirements providing a level of integrity to: Systematic Capability: SC 2 (SIL 2 Capable) **Random Capability: Type B Element** Revision 2.0 July 03, 2024 SIL 2 @ HFT = 0; Route 1_H Surveillance Audit Due PFH / PFD_{AVG} and Architecture Constraints July 1, 2027 must be verified for each application Safety Function: The 244LD LevelStar will measure Level, Interface and Density within the stated safety accuracy. **Application Restrictions:** The unit must be properly designed into a Safety Instrumented Function per the Safety Manual requirements. o Maus **Evaluating Assessor** ANSI National Accreditation Board DITED Certifying Assessor Page 1 of 2

Figure 4 - SIL 2 Capable Certificate Page 1

Figure 5 - SIL 2 Capable Certificate Page 2





Figure 6 - Report No.: Foxboro Eckardt 07/07-019 R008 Version V2, Revision R0; July 2015





Figure 8 - Management Summary Page 3



Table 1 Summary - IEC 61508 failure rates

| Failure category | SN29500 [FIT] | |
|---|---------------|--|
| Fail Safe Detected (AsD) | | |
| Fail Safe Undetected (λ _{su}) | 0 | |
| Fail Dangerous Detected (λ _{DD}) | 502 | |
| Fail Dangerous Detected (λ_{dd}), detected by internal diagnostics | 332 | |
| Fail Annunciation Detected (λ_{AD}) , detected by internal diagnostics | 24 | |
| Fail High (λ_H), detected by safety logic solver | 10 | |
| Fail Low (λ _L), detected by safety logic solver) | 136 | |
| Fail Dangerous Undetected (λ _{DU}) | 42 | |
| Fail Annunciation Undetected (AAU) | 0 | |
| No effect | 154 | |
| No part | 277 | |
| Total failure rate of the safety function (λ_{Total}) | 544 | |
| Safe failure fraction (SFF) ² | 92% | |

| Total fundre fate of the surety function (Artotal) | |
|--|-------|
| Safe failure fraction (SFF) ² | 92% |
| DCD | 92% |
| SIL AC 3 | SIL 2 |
| | |

The failure rates are valid for the useful life of the Intelligent Buoyancy Transmitter 244LD LevelStar (see Appendix 2).

² The complete sensor subsystem will need to be evaluated to determine the overall Safe Failure Fraction. The number listed is for reference only.

³ SIL AC (architectural constraints) will need to be evaluated on sensor subsystem level. The indicated value if is for reference only and means that the calculated values are within the range for hardware architectural constraints for the corresponding SIL but does not imply all related IEC 61508 requirements are fulfilled.

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Figure 9 - PFD_{AVG} Calculation



5 Using the FMEDA results

The following section describes how to apply the results of the FMEDA.

It is the responsibility of the Safety Instrumented Function designer to do calculations for the entire SIF. *exida* recommends the accurate Markov based exSILentia tool for this purpose.

The following results must be considered in combination with PFD_{AVG} values of other devices of a Safety Instrumented Function (SIF) in order to determine suitability for a specific Safety Integrity Level (SIL).

5.1 Example PFD_{AVG} calculation

An average Probability of Failure on Demand (PFD_{AVG}) calculation is performed for the Intelligent Buoyancy Transmitter 244LD LevelStar considering a proof test coverage of 95% (see Appendix 1.1) and a mission time of 10 years. The failure rate data used in this calculation are displayed in sections 0.

For SIL2 applications, the PFD_{AVG} value needs to be < 1.00E-02.

Table 2: Intelligent Buoyancy Transmitter 244LD LevelStar

| T[Proof] = 1 year | T[Proof] = 2 years | T[Proof] = 5 years |
|-------------------------------|--------------------|------------------------------|
| PFD _{AVG} = 2.92E-04 | PFDAVG =4.75E-04 | PFD _{AVG} =1.02E-03 |

Figure 6 shows the time dependent curve of $\mathsf{PFD}_{\mathsf{AVG}}$ for the Intelligent Buoyancy Transmitter 244LD LevelStar.



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