

Servo motor EMMT-AS-100-H-HS-RMB

Part number: 8182014

FESTO



Data sheet

Feature	Value
Ambient temperature	-15 °C...40 °C
Note on ambient temperature	Up to 80 °C with derating of -2.25% per degree Celsius
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-20 °C...70 °C
Relative air humidity	0 - 90 %
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	F
Max. winding temperature	155 °C
Rating class according to EN 60034-1	S1
Temperature monitoring	Digital motor temperature transmission via EnDat® 2.2
Motor type as per EN 60034-7	IM B5 IM V1 IM V3
Mounting position	Any
Degree of protection	IP40
Note on degree of protection	IP40 for motor shaft without rotary shaft seal IP65 for motor shaft with rotary shaft seal IP67 for motor housing, incl. connection technology
Concentricity, coaxiality, axial runout according to DIN SPEC 42955	N
Balancing quality	G 2.5
Detent torque	< 1.0% of peak torque
Bearing lifetime, under nominal conditions	20000 h
Interface code, motor out	100A
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connection technology	M23x1
Electrical connection 1, number of pins/wires	15
Contamination level	2
Note on materials	RoHS-compliant
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6

Feature	Value
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	RCM compliance mark c UL us - Recognized (OL)
CE marking (see declaration of conformity)	As per EU EMC directive As per EU low voltage directive As per EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions To UK instructions for electrical equipment
Certificate issuing authority	UL E342973
Nominal operating voltage DC	680 V
Type of winding switch	Star inside
Number of pole pairs	5
Stall torque	12.4 Nm
Nominal torque	7.3 Nm
Peak torque	38.7 Nm
Nominal rotary speed	2700 1/min
Max. rotational speed	5150 1/min
Max. mechanical speed	13000 1/min
Motor nominal power	2060 W
Continuous stall current	9.5 A
Motor nominal current	5.5 A
Peak current	36 A
Motor constants	1.32 Nm/A
Standstill torque constant	1.54 Nm/A
Voltage constant, phase-to-phase	93.2 mVmin
Phase-phase winding resistance	0.81 Ohm
Winding inductance phase-phase	9 mH
Winding longitudinal inductivity Ld (phase)	5.7 mH
Cross inductivity Lq (phase)	6.8 mH
Electric time constant	16.7 ms
Thermal time constant	68 min
Thermal resistance	0.39 K/W
Measuring flange	300 x 300 x 20 mm, steel
Total output inertia moment	11.09 kgcm ²
Product weight	13300 g
Permissible axial shaft load	200 N
Permissible radial shaft load	915 N
Rotor position sensor	Absolute encoder, multi-turn
Rotor position sensor for manufacturer designation	EQI 1331
Rotor position encoder for absolutely detectable revolutions	4096
Rotor position sensor interface	EnDat@ 22
Rotor position sensor measuring principle	Inductive
Rotor position encoder for DC operating voltage	5 V
Rotor position encoder for DC operating voltage range	3.6 V...14 V
Rotor position encoder for positional values per revolution	524288
Rotor position sensor resolution	19 bit
Rotor position encoder system accuracy angle measurement	-65 arcsec...65 arcsec
Brake holding torque	18 Nm
Brake DC operating voltage	24 V
Brake current consumption	1 A
Brake power consumption	24 W
Brake coil resistance	24 Ohm
Brake coil inductivity	900 mH

Feature	Value
Brake separation time	80 ms
Brake closing time	40 ms
DC brake response delay	5 ms
Max. brake no-load speed	10000 1/min
Max. brake friction work	15000 J
Brake mass moment of inertia	2.15 kgcm ²
Switching cycles, holding brake	10 million idle actuations (without friction work!)
MTTF, subcomponent	190 years, rotor position sensor
Energy efficiency	ENEFF (CN) / Class 2