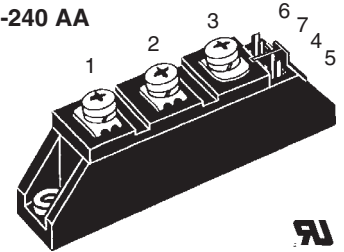


Thyristor Modules

Thyristor/Diode Modules

$I_{TRMS} = 2 \times 100 \text{ A}$
 $I_{TAVM} = 2 \times 64 \text{ A}$
 $V_{RRM} = 800-1800 \text{ V}$

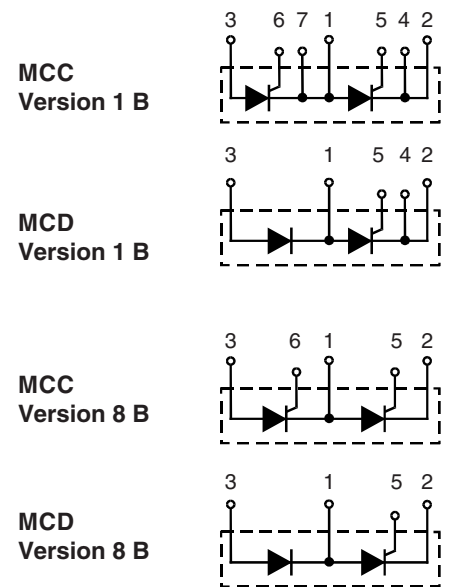
TO-240 AA



| V_{RSM} | V_{RRM} | Type | | | Type | | |
|-----------|-----------|-----------|---------------|-----------|---------------|-----|-----|
| V_{DSM} | V_{DRM} | Version | | | Version | | |
| V | V | 1 B | 8 B | 1 B | 8 B | 1 B | 8 B |
| 900 | 800 | MCC 56-08 | io1 B / io8 B | MCD 56-08 | io1 B / io8 B | | |
| 1300 | 1200 | MCC 56-12 | io1 B / io8 B | MCD 56-12 | io1 B / io8 B | | |
| 1500 | 1400 | MCC 56-14 | io1 B / io8 B | MCD 56-14 | io1 B / io8 B | | |
| 1700 | 1600 | MCC 56-16 | io1 B / io8 B | MCD 56-16 | io1 B / io8 B | | |
| 1900 | 1800 | MCC 56-18 | io1 B / io8 B | MCD 56-18 | io1 B / io8 B | | |

| Symbol | Conditions | Maximum Ratings | |
|----------------------|---|---|--|
| I_{TRMS}, I_{FRMS} | $T_{VJ} = T_{VJM}$ | 100 | A |
| I_{TAVM}, I_{FAVM} | $T_C = 83^\circ\text{C}; 180^\circ \text{ sine}$ | 64 | A |
| | $T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$ | 60 | A |
| I_{TSM}, I_{FSM} | $T_{VJ} = 45^\circ\text{C};$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | 1500 1600 A |
| | $T_{VJ} = T_{VJM}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | 1350 1450 A |
| $\int i^2 dt$ | $T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | 11 200 10 750 A^2s |
| | $T_{VJ} = T_{VJM}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | 9100 8830 A^2s |
| $(di/dt)_{cr}$ | $T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ | repetitive, $I_T = 150 \text{ A}$ | 150 $\text{A}/\mu\text{s}$ |
| | $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | non repetitive, $I_T = I_{TAVM}$ | 500 $\text{A}/\mu\text{s}$ |
| $(dv/dt)_{cr}$ | $T_{VJ} = T_{VJM};$ $R_{GK} = \infty;$ method 1 (linear voltage rise) | $V_{DR} = 2/3 V_{DRM}$ | 1000 $\text{V}/\mu\text{s}$ |
| P_{GM} | $T_{VJ} = T_{VJM};$ $I_T = I_{TAVM};$ | $t_p = 30 \mu\text{s}$ $t_p = 300 \mu\text{s}$ | 10 5 W |
| P_{GAV} | | | 0.5 W |
| V_{RGM} | | | 10 V |
| T_{VJ} | | | -40...+125 $^\circ\text{C}$ |
| T_{VJM} | | | 125 $^\circ\text{C}$ |
| T_{stg} | | | -40...+125 $^\circ\text{C}$ |
| V_{ISOL} | 50/60 Hz, RMS; $I_{ISOL} \leq 1 \text{ mA};$ | $t = 1 \text{ min}$ $t = 1 \text{ s}$ | 3000 3600 $\text{V}\sim$ |
| M_d | Mounting torque (M5) Terminal connection torque (M5) | | 2.5-4.0/22-35 2.5-4.0/22-35 $\text{Nm}/\text{lb.in.}$ |
| Weight | Typical including screws | | 90 g |

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated. IXYS reserves the right to change limits, test conditions and dimensions



Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded Al_2O_3 -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1B

Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

| Symbol | Conditions | Characteristic Values | |
|--------------------|---|-----------------------|------------------|
| I_{RRM}, I_{DRM} | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$ | 5 | mA |
| V_T, V_F | $I_T/I_F = 200 \text{ A}; T_{VJ} = 25^\circ\text{C}$ | 1.57 | V |
| V_{T0} | For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$) | 0.85 | V |
| r_T | | 3.7 | m Ω |
| V_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | 1.5 | V |
| | $T_{VJ} = -40^\circ\text{C}$ | 1.6 | V |
| I_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | 100 | mA |
| | $T_{VJ} = -40^\circ\text{C}$ | 200 | mA |
| V_{GD} | $T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$ | 0.2 | V |
| I_{GD} | | 10 | mA |
| I_L | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}; V_D = 6 \text{ V}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | 450 | mA |
| I_H | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$ | 200 | mA |
| t_{gd} | $T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | 2 | μs |
| t_q | $T_{VJ} = T_{VJM}; I_T = 150 \text{ A}; t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$ | typ. 150 | μs |
| Q_S | $T_{VJ} = T_{VJM}; I_T, I_F = 50 \text{ A}, -di/dt = 3 \text{ A}/\mu\text{s}$ | 100 | μC |
| I_{RM} | | 24 | A |
| R_{thJC} | per thyristor/diode; DC current per module | 0.45 | K/W |
| R_{thJK} | per thyristor/diode; DC current per module | 0.225 | K/W |
| | other values see Fig. 8/9 | 0.65 | K/W |
| | | 0.325 | K/W |
| d_s | Creepage distance on surface | 12.7 | mm |
| d_A | Strike distance through air | 9.6 | mm |
| a | Maximum allowable acceleration | 50 | m/s ² |

Optional accessories for module-type MCC 56 version 1 B
 Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red
 Type **ZY 200L** (L = Left for pin pair 4/5) } UL 758, style 1385,
 Type **ZY 200R** (R = right for pin pair 6/7) } CSA class 5851, guide 460-1-1

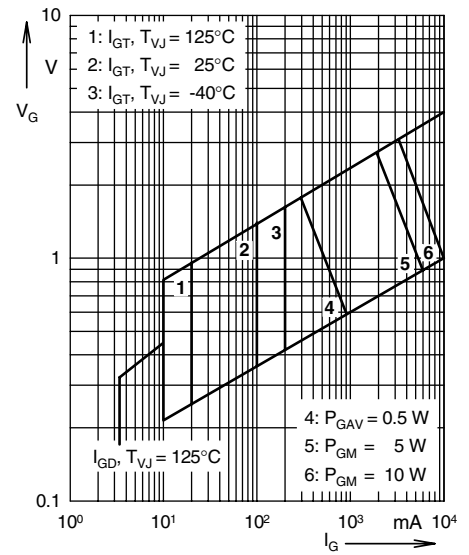


Fig. 1 Gate trigger characteristics

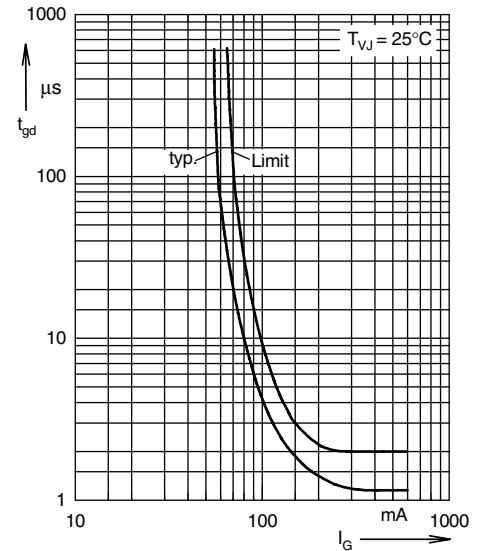
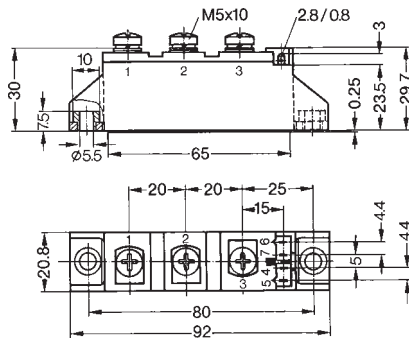


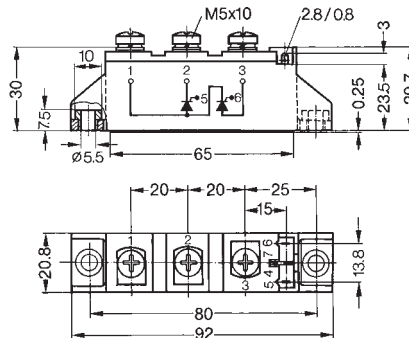
Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

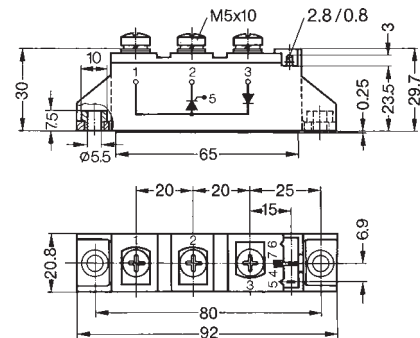
MCC / MCD / MDC Version 1 B



MCC Version 8 B



MCD Version 8 B



Version 1 or 8 without B in type designation = without insert in mount holes

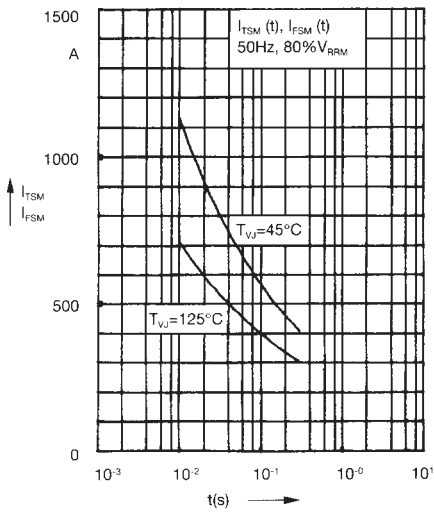


Fig. 3 Surge overload current
 I_{TSM} , I_{FSM} : Crest value, t: duration

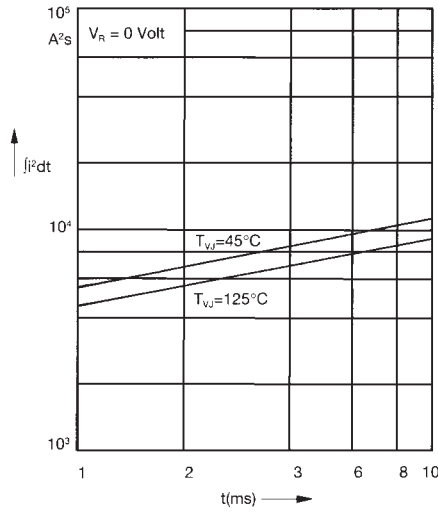


Fig. 4 $\int i^2 dt$ versus time (1-10 ms)

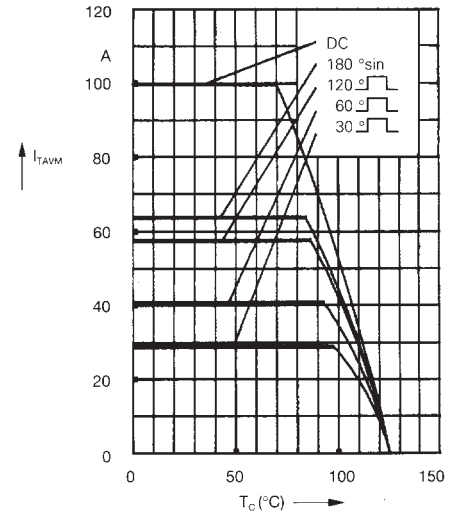


Fig. 4a Maximum forward current at case temperature

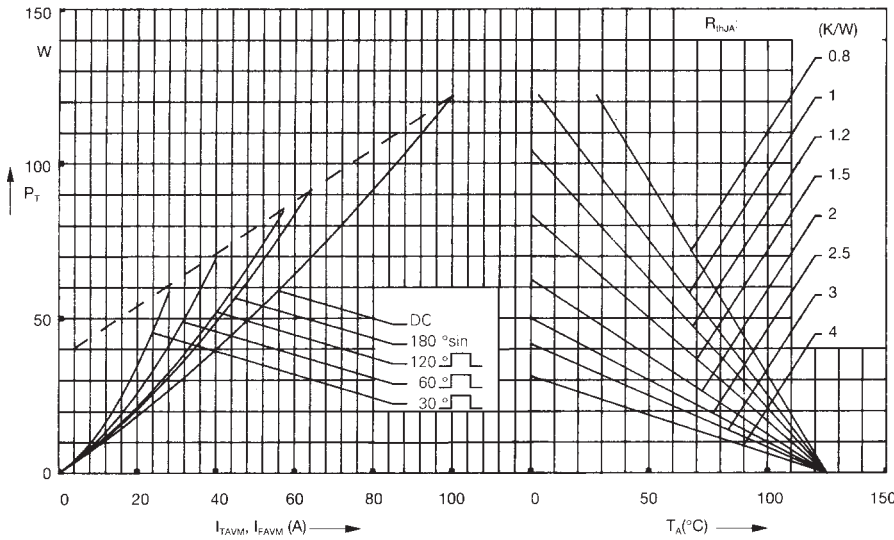


Fig. 5 Power dissipation versus on-state current and ambient temperature (per thyristor or diode)

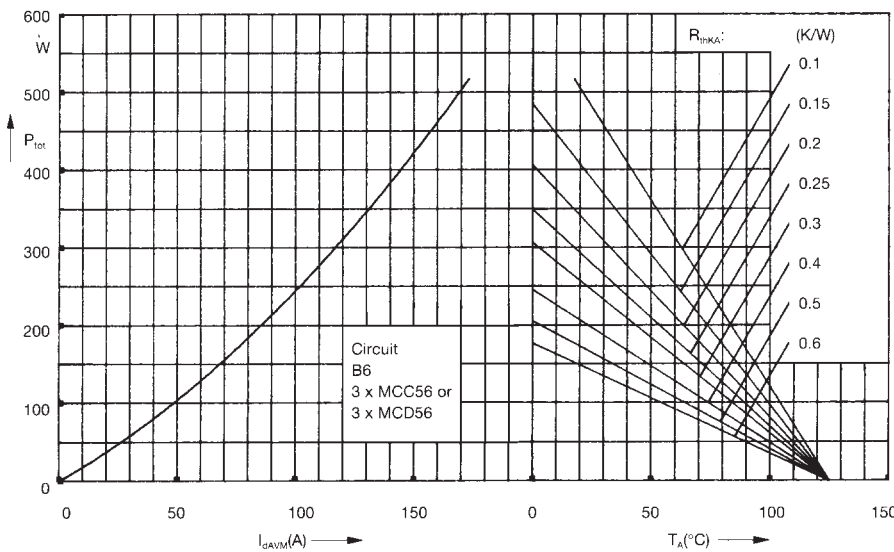


Fig. 6 Three phase rectifier bridge: Power dissipation versus direct output current and ambient temperature

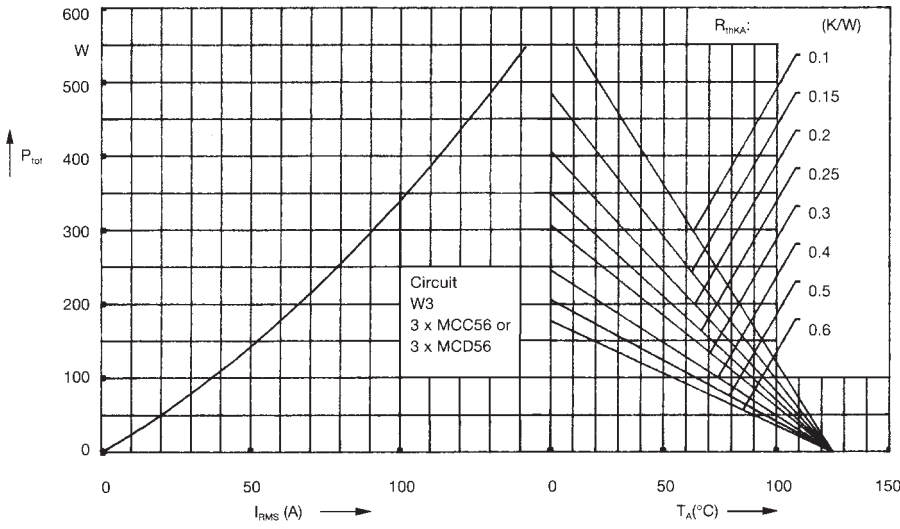


Fig. 7 Three phase AC-controller: Power dissipation versus RMS output current and ambient temperature

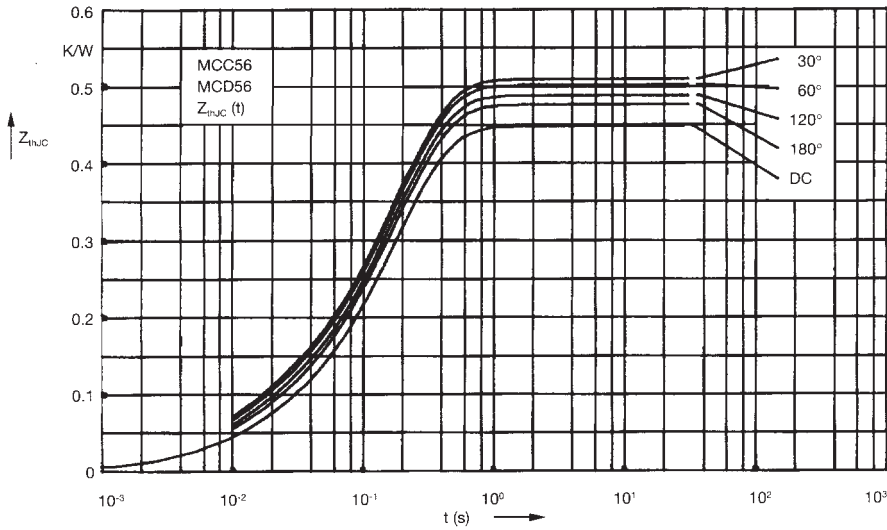


Fig. 8 Transient thermal impedance junction to case (per thyristor or diode)

R_{thJC} for various conduction angles d:

| d | R_{thJC} (K/W) |
|------|------------------|
| DC | 0.45 |
| 180° | 0.47 |
| 120° | 0.49 |
| 60° | 0.505 |
| 30° | 0.52 |

Constants for Z_{thJC} calculation:

| i | R_{thi} (K/W) | t_i (s) |
|---|-----------------|-----------|
| 1 | 0.014 | 0.015 |
| 2 | 0.026 | 0.0095 |
| 3 | 0.41 | 0.175 |

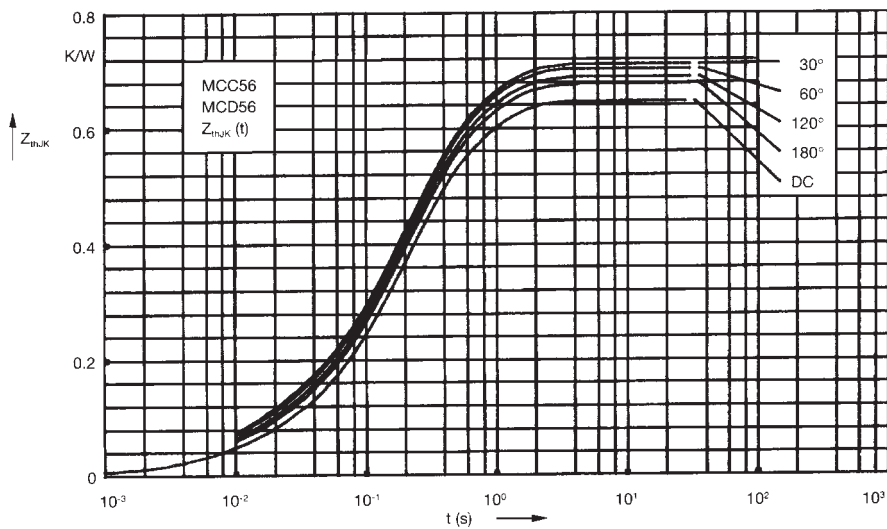


Fig. 9 Transient thermal impedance junction to heatsink (per thyristor or diode)

R_{thJK} for various conduction angles d:

| d | R_{thJK} (K/W) |
|------|------------------|
| DC | 0.65 |
| 180° | 0.67 |
| 120° | 0.69 |
| 60° | 0.705 |
| 30° | 0.72 |

Constants for Z_{thJK} calculation:

| i | R_{thi} (K/W) | t_i (s) |
|---|-----------------|-----------|
| 1 | 0.014 | 0.015 |
| 2 | 0.026 | 0.0095 |
| 3 | 0.41 | 0.175 |
| 4 | 0.2 | 0.67 |